

# H-Bridge Demystified

- Basic electronic theory
- How H-Bridges work
- Explain terminology
- Explain where the power goes

# Basic Theory: Ohms law

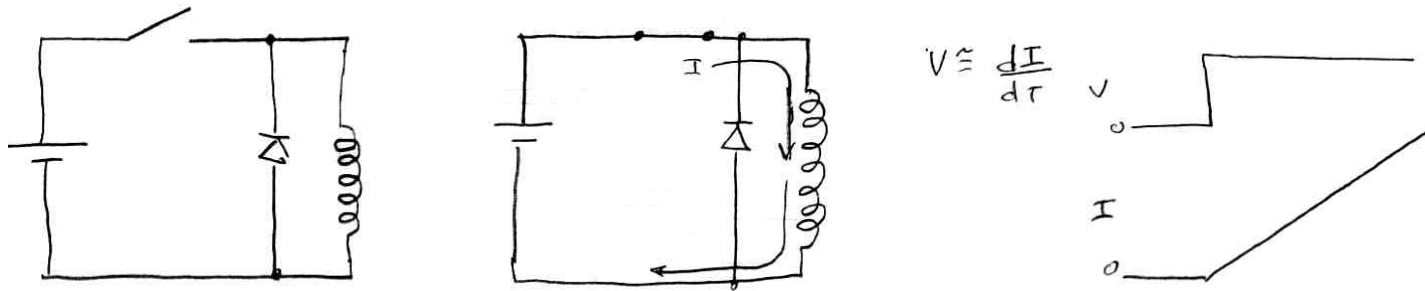
- $\text{Power} = \text{Voltage} * \text{Current}$
- $\text{Voltage} = \text{Current} * \text{Resistance}$

Examples:

- $.5\text{A} * 10 \text{ ohms} = 5\text{v}$
- $5\text{v} * .5\text{A} = 2.5 \text{ watts}$
- $.5\text{v} / .05 \text{ ohms} = 10\text{a}$
- $10\text{a} * .5\text{v} = 5 \text{ watts}$
- $\text{Power} = \text{Current}^2 * \text{resistance}$

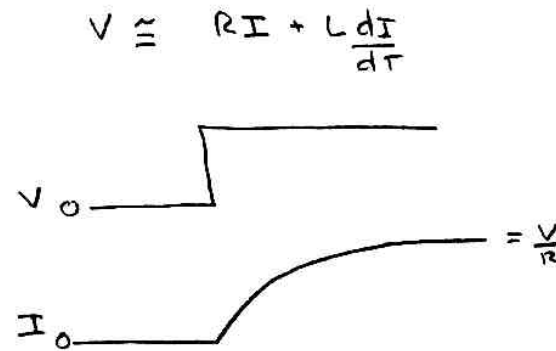
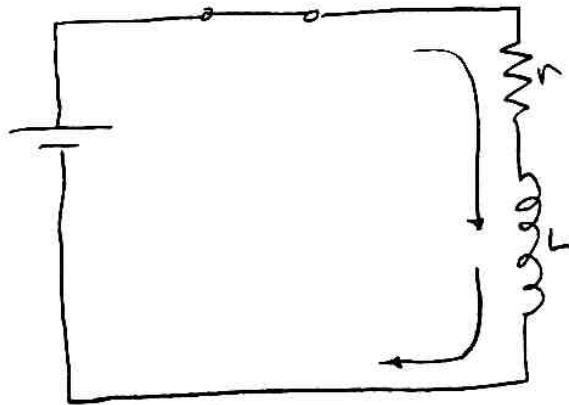
# Basic Theory: Inductors

- $V = L * dI/dT$  - What does that mean???



- Current rises indefinitely based upon inductance and voltage.

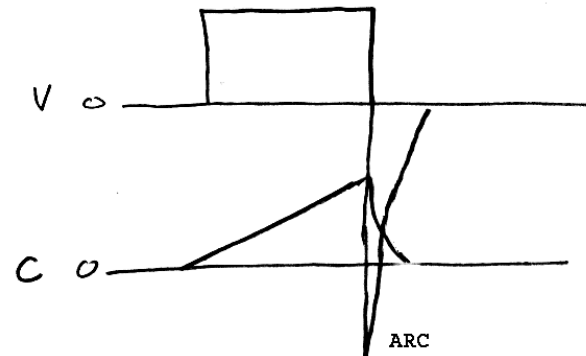
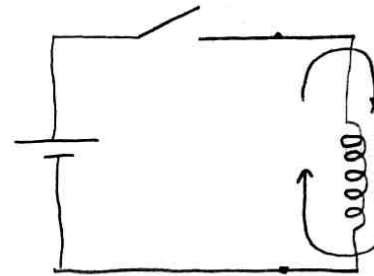
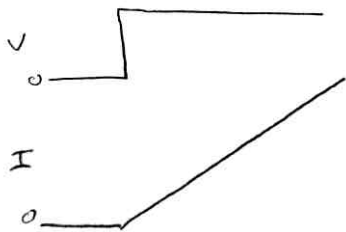
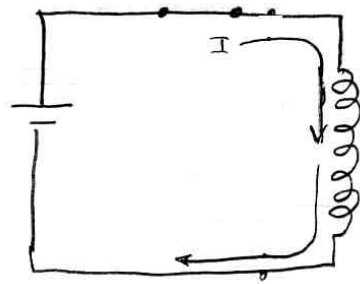
# Basic Theory: Real Inductors



- Real inductors have resistance
- Current \* resistance = voltage
- Eventually current levels out
- Strength of magnetic field + level of stored energy are proportional to the current.

# Basic Theory: Inductors

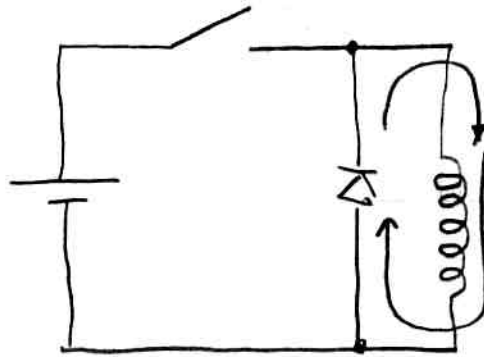
- What happens when switch is opened?



- Current dissipates quickly in the ARC

# Basic Theory: Inductors

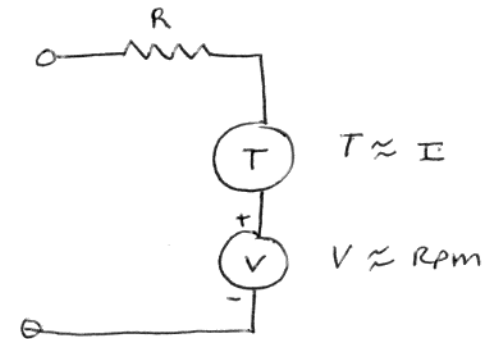
- Diodes used to suppress arcing
- Recirculating currents dissipate slower



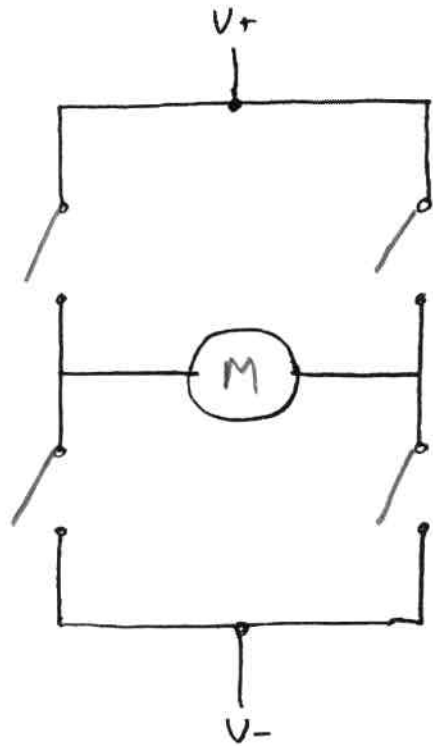
- Note: current continues to flow in inductor
- Power is dissipated across diode & inductor internal resistance.

# Basic Theory: PMDC motor

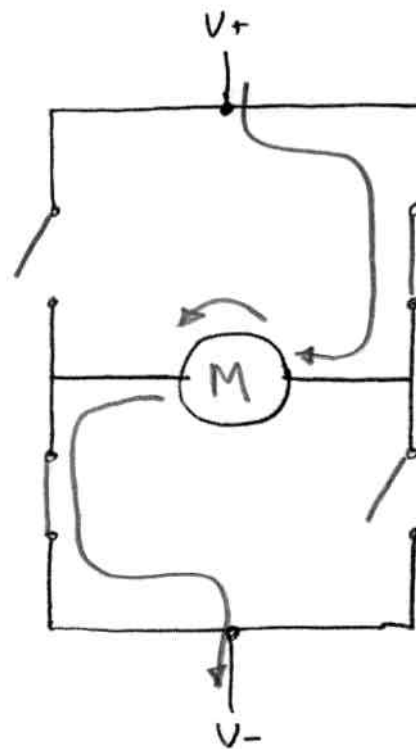
- PMDC motors can be modeled as an inductor, a voltage source and a resistance.
- Torque is proportional to the current
- The internal voltage source is proportional to the RPM (Back-EMF)
- Stall current/max torque is proportional to the internal resistance.



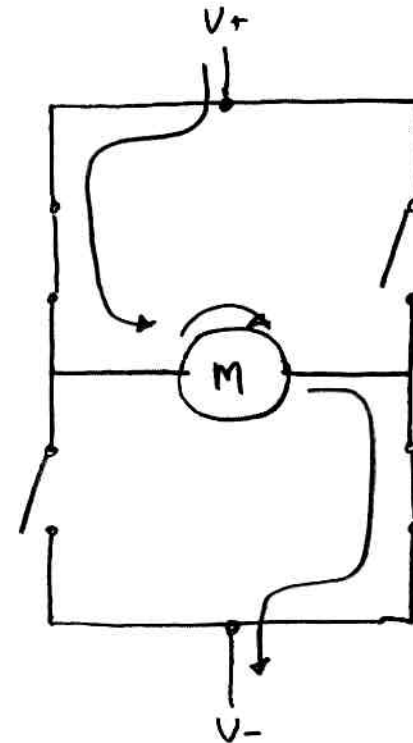
# How H-Bridge works



Off

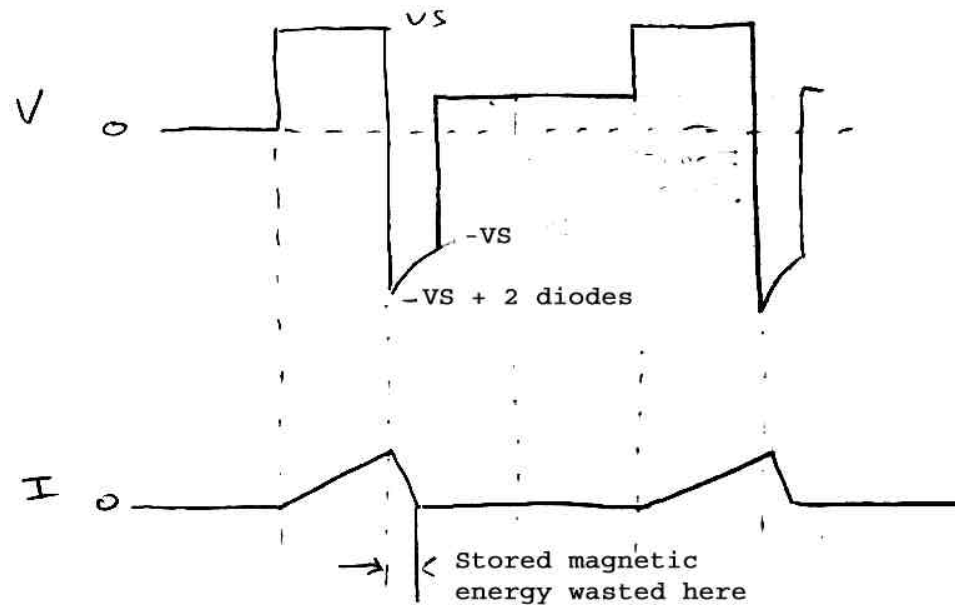
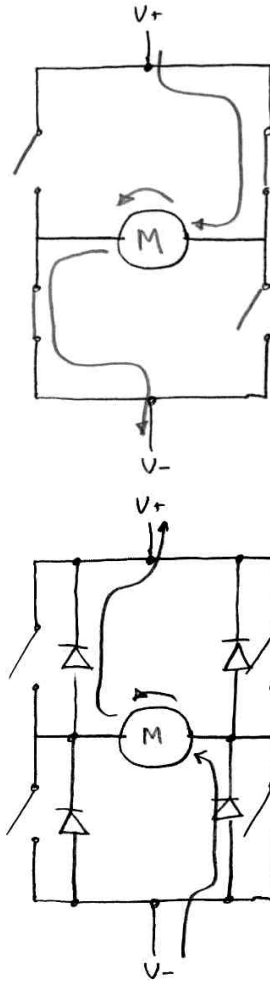


Forward



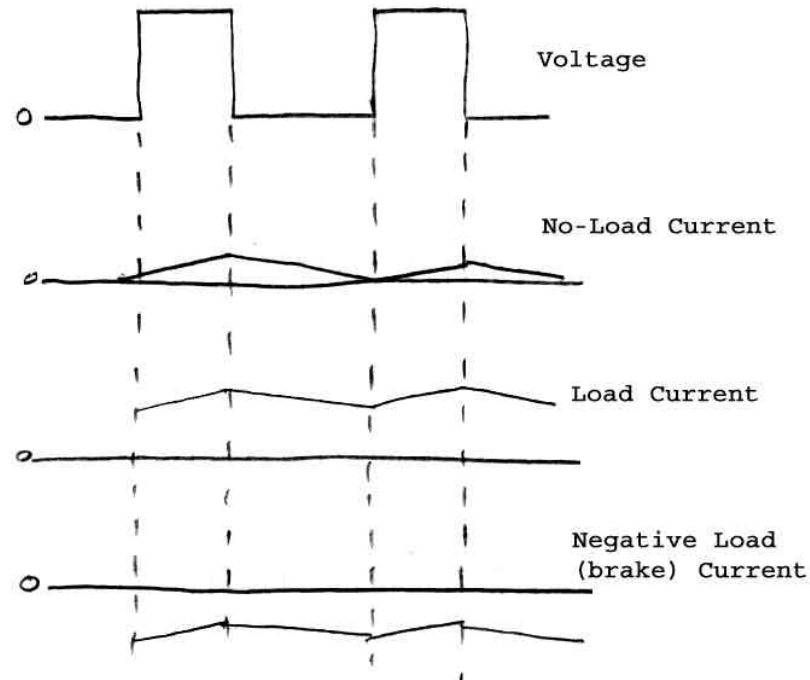
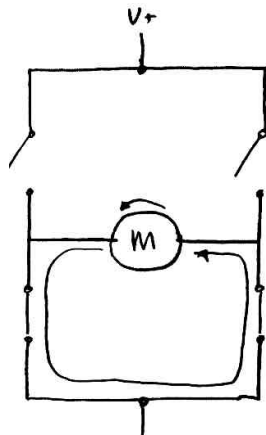
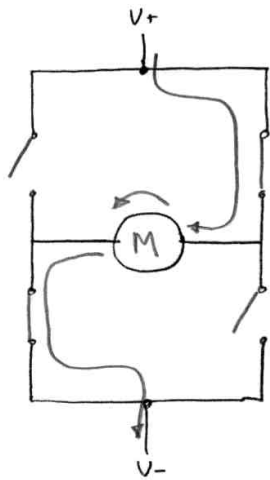
Reverse

# How H-Bridge Works



- This represents traditional PWM motor control
- Note low average current flow

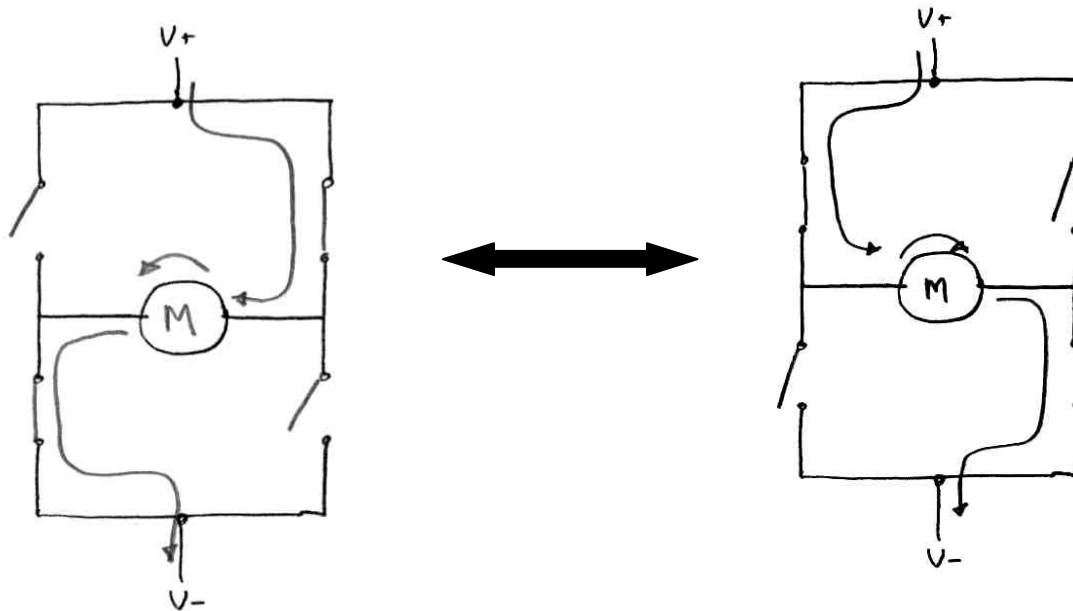
# H-Bridge: Synchronous Rectification



- Use switches instead of diodes
- Much more efficient, regenerative braking

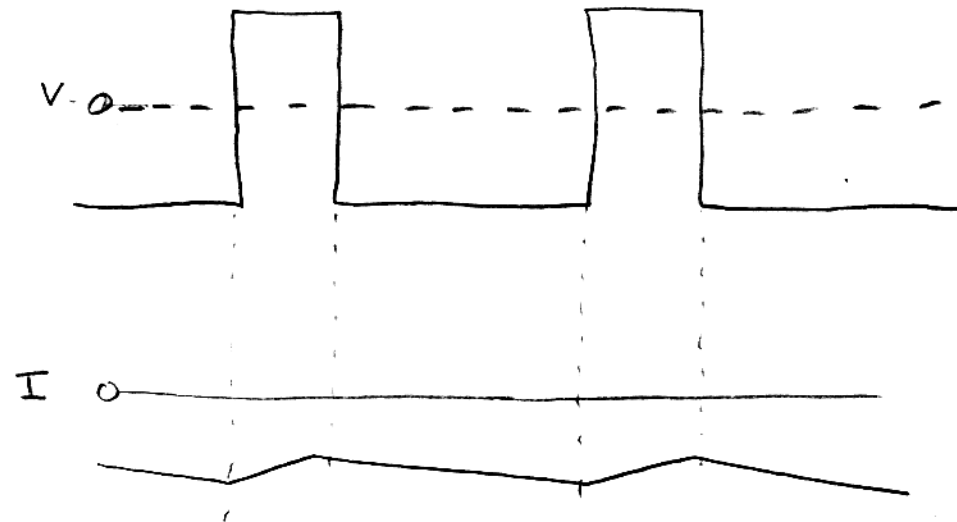
# H-Bridge Locked-Antiphase

- Pro: one line needed for forward/reverse
- Con: higher frequencies needed



# Locked Antiphase

- Voltage swings from  $+V$  to  $-V$
- No rectification needed
- Current ripple twice as large



# H-Bridge Examples

L293, L298, MC33886, TLE5206, TPIC0108b, etc

Simple logic: output = input. Some chips have disables to disconnect all outputs. Advance chips output protection.

Functional Truth Table				
IN1	IN2	OUT1	OUT2	Comments
L	L	L	L	Brake; both low transistors on
L	H	L	H	Forward
H	L	H	L	Reverse
H	H	H	H	Brake; both high transistors on.

# H-Bridge Examples

LM18200, TLE5205, TPIC0107b, etc.

Functional Truth Table (LM18200)					
PWM	DIR	Brake	OUT1	OUT2	Comments
H	H	L	H	L	Forward
H	L	L	L	H	Reverse
L	X	L	H	H	High Side BRAKE
H	H	H	L	L	Low Side Brake
H	L	H	L	L	Low Side BRAKE
L	X	H	Z	Z	None

# Demonstration

- Actual current flow & voltage charts
- Resistor
- Inductor (motor)
  - No load
  - Load (power delivered)
  - Negative Load (Regenerative braking)

# H-Bridge/Inductor Demonstration

